

# Techniques to evaluate the mass sensitivity of Love mode surface acoustic wave biosensors

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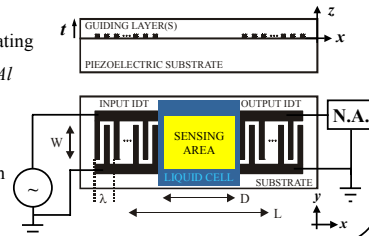
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## INTRODUCTION

- Love mode:** shear-horizontal surface acoustic wave guided in single or multiple layer coatings on a piezoelectric substrate
- Biosensing:** acoustic signal (delay phase angle and insertion loss) shifts caused by the adsorption of biomolecules from a liquid medium (e.g. antibodies in blood sample)
- Purpose of the research:** experimental and theoretical investigation of the sensing characteristics of the Love mode device for its application as biosensor

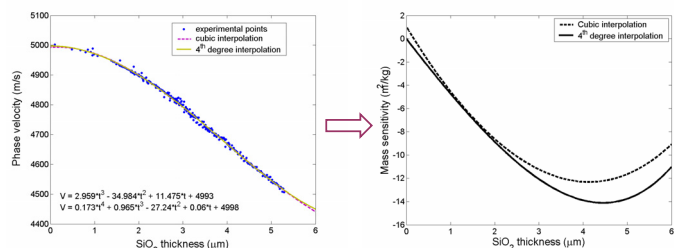
## LOVE MODE SAW BIOSENSOR

- Structure: ST-cut quartz substrate  
 $t = 1.2 \mu\text{m}$  PECVD  $\text{SiO}_2$  coating
- IDT: 100 split fingers pairs of 200 nm Al
- Center frequency  $f_0 = 123.5 \text{ MHz}$
- Wavelength  $\lambda = 40 \mu\text{m}$ ,  $L = 9 \text{ mm}$
- Sensing area:  $D = 4.7 \text{ mm}$ ,  $W = 3.2 \text{ mm}$  covered with 50 nm Au
- Static liquid cell above sensing area



## EXPERIMENTAL TECHNIQUES

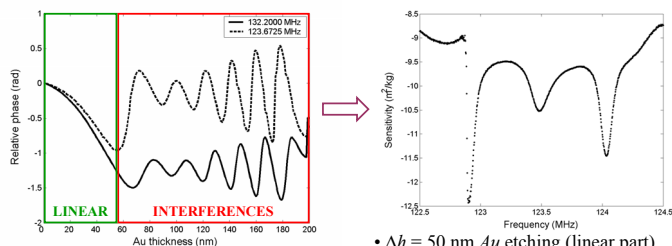
### 1) Experimental measurement of the dispersion curve



- Thick PECVD  $\text{SiO}_2$  ( $> 5 \mu\text{m}$ ) wet etching in fluorhydric acid
- Continuous monitoring of the transfer function during the etching
- Mass sensitivity obtained by derivation of the dispersion curve

### 2) Sensitivity evaluated by modifying the surface density $\Delta\sigma$

#### ✓ Gold thin film etching: $\Delta\sigma = \rho \Delta h$



- 200 nm gold etching  $\uparrow$  in  $KI/I_2$
- $\Delta h = 50 \text{ nm Au}$  etching (linear part)
- $\rho = 19300 \text{ kg/m}^3 \rightarrow \Delta\sigma = 96500 \text{ ng/cm}^2$
- Parasitic interferences enhanced by Au

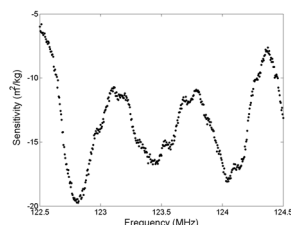
#### ✓ Copper electrodeposition: $\Delta\sigma \sim \text{current}$

- Sensing area = working electrode
- Rough surface:
  - hydrodynamic drag effect
  - overestimated mass sensitivity:  $S_{\phi,\sigma} = -27.43 \pm 1.74 \text{ m}^2/\text{kg}$

$\Delta\sigma$ ( $\text{ng/cm}^2$ )	$\Delta\phi$ (mrad)	$\Delta\alpha/\Delta\phi$ (dB/rad)
$1286 \pm 75$	$-255.8 \pm 16.6$	$-2.20 \pm 0.47$
$3534 \pm 53$	$-737.6 \pm 5.5$	$-1.77 \pm 0.06$
$3928 \pm 107$	$-785.8 \pm 15.2$	$-1.79 \pm 0.12$

#### ✓ CTAB adsorption: $\Delta\sigma \sim \text{surface coverage}$

- Small molecule ( $M_w = 365 \text{ g/mol}$ )
- Monolayer formation:  $\Delta\sigma = 137 \text{ ng/cm}^2$
- Attenuation  $<$  noise level (0.05 dB)
- Surface coverage  $\sim$  solution concentration



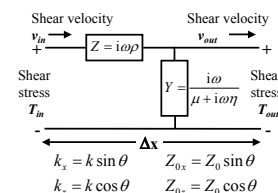
- Surface density or viscous thin layer?  $\rightarrow$ 
  - similar phase and attenuation shifts
  - distinction density/viscosity impossible

	Rigid $h = 1.5 \text{ nm}$	Viscous $h > 3\delta$
$\Delta\phi$ (mrad)	-17	-20
$\Delta\alpha$ (dB)	0.01	0.005
		2.35

## THEORETICAL TECHNIQUE

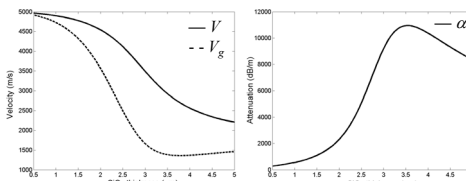
### ✓ Mechanical transmission lines model

- Block approach** for each layer of the structure with density  $\rho$ , shear stiffness  $\mu$ , viscosity  $\eta$
- Parallel/series connection along  $x/z$  directions
- Complex coupling angle  $\theta$
- Transverse resonance principle**



### • Dispersion curve $\rightarrow$

- phase velocity  $V(t)$
- group velocity  $V_g(t)$
- attenuation  $\alpha(t)$



### ✓ Sensitivity evaluation

- Mass sensitivity:

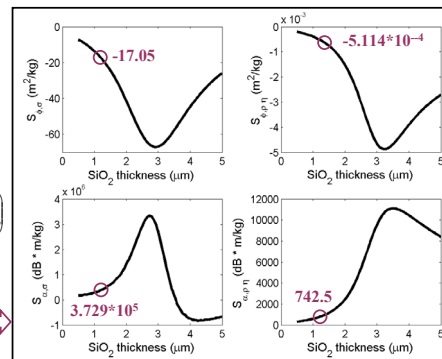
$$S_{\phi,\sigma} = \frac{1}{V} \frac{dV}{d\sigma} \cong \frac{1}{\rho t} \frac{V_g - V}{V}$$

- Sensor response model:

$$\begin{pmatrix} d\phi \\ d\alpha \end{pmatrix} = \begin{pmatrix} kD & 0 \\ 0 & D \end{pmatrix} \begin{pmatrix} S_{\phi,\sigma} & S_{\phi,\eta} \\ S_{\alpha,\sigma} & S_{\alpha,\eta} \end{pmatrix} \begin{pmatrix} d\sigma \\ d\eta \end{pmatrix}$$

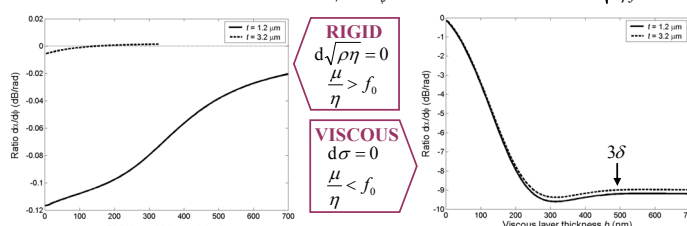
Structure Intrinsic S

$$\begin{pmatrix} \frac{1}{\rho} \frac{dV}{d\sigma} \\ \frac{d\alpha}{d\sigma} \end{pmatrix} \begin{pmatrix} \frac{1}{V} \frac{dV}{d\eta} \\ \frac{d\alpha}{d\eta} \end{pmatrix}$$



### ✓ Rigid or viscous sensing?

- Ratio attenuation shift to phase shift:  $\frac{d\alpha}{d\phi} = \frac{S_{\alpha,\sigma}}{kS_{\phi,\sigma}}$
- Decay length:  $\delta \cong \sqrt{\frac{\eta}{\rho f}}$



- Theoretical value for  $\lim h \rightarrow 0$
- Sensitive to  $\text{SiO}_2$  thickness

- Theoretical value for  $h > 3\delta$
- Insensitive to  $\text{SiO}_2$  thickness

### ✓ Biosensing = viscous sensing

- $\mu/\eta$  from  $\sim 1$  to  $\sim 10 \text{ MHz} < f_0$
- $h$  from  $\sim 1$  to  $\sim 20 \text{ nm} < 3\delta_{\text{water}} (150 \text{ nm})$
- Calibration by viscous solutions not enough to evaluate  $S_{\phi,\eta}(h)$  and  $S_{\alpha,\eta}(h)$

$\rightarrow$  BIOSENSING = VISCIOUS SENSING with unknown parameters:  $\rho, \eta$  and  $h$

## CONCLUSION

- Mixed contribution of density and viscosity interactions for biomolecules

- Modeling is needed to extract both contributions to the acoustic signal