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Piezoelectric acoustic transducers as narrowband passive sensors for wireless measurement in the European ISM band (434 MHz): application to the measurement of the temperature of buried structures

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March 3, 2012



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Outline of the presentation

Objective:

solution for buried/embedded sensors for structural health monitoring ${\bf Requirements}$ for embedded sensors:

- Problem of local energy source: how to replace battery when the sensor is buried or in concrete ? (WSN¹²)
- External energy source: excessive time lapse needed to charge circuit
- RFID will not provide measurement + short range
- Solution: passive sensors interrogated through a wireless link

Outline:

- 1 Acoustic sensor basics and properties
- Application to wireless measurement of passive transducers using custom reader electronics
- 3 Ground Penetrating RADAR (GPR) for SAW delay lines

4 Extension to HBAR

¹K.M. Farinholt, G. Park, C.R. Farrar, *RF energy transmission for low-power wireless impedance sensor node*, IEEE Sensors Journal **9** (7), 2009 793-900

²S.G. Taylor, K.M Farinholt, G. Park, C.R. Farrar, Energy harvesting and wireless energy transmission for powering SHM Sensor Nodes, Los Alamos report (2010) available at permalink.lanl.gov/object/tr?what=info:lanl=repo/lareport/Lk=UR-09-07854 ~ 0, ~

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Embedded sensor requirements

- Sensors = dielectric or piezoelectric substrate.
- Piezoelectric is the most compact way of converting incoming radiofrequency (RF) energy to a mechanical wave acting as physical quantity probe
- Rich field thanks to the anisotopic property of piezoelectric materials (sensitive or insensitive to given physical effects)
- Competitive: RF filter & resonator industry (Murata, Taisaw, Rakon, EPCOS, Triquint, ...) ← cost-effective mass production of the considered technology (single patterned metallic layer step)

'TCF1' -----



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A **piezoelectric** substrate converts incoming RF signal to a mechanical wave: two approaches

Basics

▲ □ ▶ ▲ □

-

- store energy and release it during the listening step: resonator (narrowband, frequency output)
- impulse response: delay line approach (wideband, time delay output)



Lower frequency in order to improve penetration depth of RF signal in dielectrics, within acceptable antenna dimension limits and RF emission compliance (315 & 426 MHz in Japan, 434 MHz in Europe)

Linear process: whatever incoming energy reaches the sensor, some signal will be returned (no threshold), but can only be detected if above the receiving stage noise level.

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Frequency domain approach (resonators)

- Low loss device (most incoming energy is stored and released during the listening step)
- Dedicated electronics: frequencysweep, monostatic pulse mode RADAR



- Time constant: $Q/(\pi f)$ for a resonator operation at $f \simeq 434$ MHz and $Q \simeq 10000$: 6 μs
- Typical interrogation duration: 128 points over 2 MHz wide ISM band, 60 μ s/sample = 8 ms
- Compatible with intermittently visible sensors (rotating & moving part)



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Measurement strategy:

frequency sweepmonostatic RADAR interrogation



① program frequency synthesizer at frequency f

2 send RF pulse for a duration longer than $Q/(\pi f)$ s (resonator load)

Wireless measurement (frequency)

- **3** switch antenna from emission (synthesizer + power amplifier) to reception (low noise amplifier + power detector)
- ④ record magnitude of returned signal (wideband power detector) within the frequency interrogation range after a duration < $Q/(\pi f)$ (resonator energy release)
- **5** $f \rightarrow f + \Delta f$ & repeat for all values of f in interrogation band ^{3 4}

³ J.-M Friedt, C. Droit, G. Martin & S. Ballandras, A wireless interrogation system exploiting narrowband acoustic resonator for remote physical quantity measurement, Rev. Sci. Instrum. **81**, 014701 (2010)

⁴ C. Droit, G. Martin, S. Ballandras & J.-M Friedt, A frequency modulated wireless interrogation system exploiting narrowband acoustic resonator for remote physical quantity measurement, Rev. Sci Instrum. 81 (5), 056103 (2010) < = > < =>

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Frequency domain approach (resonators)

Moving objects: main parameter is angular coverage of the rotating (sensor) antenna and static (interrogation unit) antenna.

5000 RPM electric motor



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Moving objects: main parameter is angular coverage of the rotating (sensor) antenna and static (interrogation unit) antenna.

up to 280 km/h motorbike tire



5 sensors located around a wheel, frequency multiplexing, data cleaned using a standard deviation criterion

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Frequency domain approach (resonators)

Long term monitoring of temperature sensors buried 30, 60 (dead) and 80 cm deep

Robust solution: no cable, resistant to lawn mowing, no visible drift, measurements consistent with reference data (www.meteociel.fr)⁵





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Double glazing window insulation

- Two temperature sensors, one indoor and one outdoor (dipole),
- 5 second measurements every 5 minutes,
- Bluetooth link between interrogation unit and laptop connected to the internet (http://sequanux.org/jmfriedt/t/resultat.html)



10 m interrogation range using a 5-element Yagi-Uda antenna, no correction to the original calibration data obtained in climatic chamber

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Reference curve: http://www.wunderground.com/weatherstation/ WXDailyHistory.asp?ID=IFRANCHE6, 12 km_away

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Application to civil engineering structure health monitoring

Sensor buried \simeq 3 cm deep in wet concrete (accelerated hardening)





- Objective: assess concrete curing condition.
- Passive sensor ⇒ no battery leakage, but requires antenna (beware of reinforced concrete)
- Applicable to stress sensor

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- Frequencydomain approach

Temperature: easiest (sensor mechanically isolated from environment),

Detected quantities

stress - no identifiable dependence of strain coefficient wrt temperature⁶ \Rightarrow **pressure** (strain gauge on a membrane)



- Resulting sensitivity: $\Delta f/f \in [-20..+20]$ ppm/MPa, max stress (quartz) <250 MPa, *i.e.* $\Delta f \leq 2$ MHz at 434 MHz
- Challenge: linking stiff strain gauge (quartz) to stiff substrate (steel)

⁶S. Alzuaga, É. Michoulier, J. Masson, J.-M Friedt, G. Martin, P. Berthelot, V. Pétrini & S. Ballandras, Characterization of the thermal dependance of SAW stress sensitivity. CFA 2010, available at http://cfa.sfa.asso.fr/cd1/data/articles/000218.pdf 🔗 🛇

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Temperature: easiest (sensor mechanically isolated from environment),

Detected quantities

 stress – no identifiable dependence of strain coefficient wrt temperature⁶ ⇒ pressure (strain gauge on a membrane)



• Interrogation strategy for probing the sensor at 4.8 kHz

6S. Alzuaga, É. Michoulier, J. Masson, J.-M Friedt, G. Martin, P. Berthelot, V. Pétrini & S. Ballandras, *Characterization of the* thermal dependance of SAW stress sensitivity, CFA 2010, available at http://cfa.sfa.asso.ft/@dl/data/articles/000218.jpdf 🔗 🔍

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Time-domain approach

- Fancy interrogation strategies exist, but the most simple approach aims at recording the impulse response
- Probe delay line sensor with a single RF pulse, and time difference between returned pulses is a function of measurement quantity
- High losses in this simple approach, but *compatible with existing* equipment
- Acoustic delay line provide measurement capability to Ground Penetrating RADAR (GPR) classically used for structure health monitoring and road condition assesment



Most simple use: identification. But efficient signal processing for retrieving physical quantity.

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Wireless measurement (time)



^I J.-M. Friedt, T. Rétornaz, S. Alzuaga, T. Baron, G. Martin, T. Laroche, S. Ballandras, M. Griselin & J.-P. Simonnet, *Surface* acoustic wave devices as passive buried sensors, J. Appl. Phys. 109 (3), 2011, 034905 □ → ∢ 合 → ◇ ⊲ (→

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Measurement example: delay line probed with GPR

Method: record on a long enough duration to observe all reflected pulses from delay line (typically \leq 5 μ s, *i.e.* 425 m-deep reflectors in ice)



Post-processing: the hyperbola curvature of the acoustic sensor is inconsistent with the assumed depth of a dielectric reflector \Rightarrow easy identification of the acoustic response after migration

Curvature of the hyperbola \leftrightarrow depth of the sensor.

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Measurement example: delay line probed with GPR

Method: record on a long enough duration to observe all reflected pulses from delay line (typically $\leq 5 \ \mu$ s, *i.e.* 425 m-deep reflectors in ice)



100 MHz

200 MHz

Post-processing: the hyperbola curvature of the acoustic sensor is inconsistent with the assumed depth of a dielectric reflector \Rightarrow easy identification of the acoustic response after migration

Curvature of the hyperbola \leftrightarrow depth of the sensor.

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• Distance between reflected pulses provides the physical quantity.

Measurement example: delay line

- Phase of the Fourier transform for accurate delay estimate (rather than magnitude of the time domain signal). Alternative: cross correlation.
- Only data post-processing, no modification on the original hardware.
- But piezoelectric conversion efficiency $(K^2) \Rightarrow$ losses: typical insertion losses in the 35 dB range. Hence the interrogation range estimate: $d_{SAW} = d_{ice-rock} \times 10^{(L_{ice-rock} \square L_{SAW})/A0_{(\frac{1}{2})} + \frac{1}{2}} \Rightarrow 200^{\circ}$

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High-overtone Bulk Acoustic Resonator (HBAR)

- Latest research activity: a single sensor compatible with multiple GPR operating frequencies,
- mix between delay line and frequency domain approach (frequency comb is also a time-domain pulse comb),
- if neighbouring responses exhibit different sensitivity to measured quantity: differential sensor.
- thin single-crystal piezoelectric layer ⁸
- wafer scale assembly, ⁹

⁸ T. Baron, D. Gachon, G. Martin, S. Alzuaga, D. Hermelin, J.-P. Romand, S. Ballandras, *Temperature Compensated Radio-Frequency Harmonic Bulk Acoustic Resonators*, Proceedings of IEEE International Frequency Control Symposium (2010)

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High-overtone Bulk Acoustic Resonator (HBAR)

Coupled resonators between the thin piezoelectric film and low acoustic loss (thick) substrate



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High-overtone Bulk Acoustic Resonator (HBAR)

Coupled resonators between the thin piezoelectric film and low acoustic loss (thick) substrate



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Interrogation strategies



interrogation

- Closed loop (oscillator) is challenging due to the multimode response
- Open-loop interrogation strategy suitable for this multimode transducer
- Fourier transform of a frequency comb is a series of time-domain pulses \Rightarrow can be used either as a narrowband transducer (frequency domain) or a wideband, multimode device (time domain)

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Wireless measurement (frequency)

Experimental setup: SENSeOR interrogation unit programmed to probe 432-434 MHz range (128 frequency steps), 16 averages (\simeq 120 ms/measurement)



wideband

narrowband

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Wireless measurement (frequency)

Experimental setup: SENSeOR interrogation unit programmed to probe 432-434 MHz range (128 frequency steps), 16 averages (\simeq 120 ms/measurement)



Experimental setup



selected resonance at 431.92495 MHz

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Wireless measurement example

Measurement example: one resonance frequency as a function of temperature, for one temperature compensated HBAR (black) and one temperature sensivite HBAR (sensor: green & blue): wireless, $f \in [431 - 343]$ MHz.



 \Rightarrow differential frequency measurement strategy available (reduces sensor and local oscillator aging drift + correlated noise sources)

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Wireless measurement (time)

- Resonance over a wide frequency range ⇒ the same HBAR is compatible with multiple RADAR frequencies ¹⁰ (in Ground Penetrating RADAR: defined by antenna dimensions)
- here all reflections are from the same acoustic mode: a sensor will require different modes exhibiting different sensitivities with respect to the physical quantity under investigation





Left: the same HBAR probed with a Malå RAMAC GPR equipped with 100 (top) and 200 MHz (bottom) antennas

10 T. Rétornaz, J.-M Friedt, S. Alzuaga, T. Baron, É. Lebrasseur, G. Martin, T. Laroche, S. Ballandras, M., Griselin, J.-P. Simonnet, Q. C. Indian Workshop'12 Piezoelectric radiofrequency transducers as passive buried sensors, Nondestructive Testing and Evaluation (accepted 2012)

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demonstrated solution for buried/isolated/mobile sensors interrogated through a wireless link, no local energy source

• robust solution (temperature>160°C), linear interrogation process \Rightarrow extended interrogation range, up to 12 m using directive antenna,

Conclusion

SOA

- frequency based (narrowband) and time based (wideband) interrogation strategies,
- use of commercially available Ground Penerating RADAR equipment, requiring only post-processing (no hw modification),
- ability to select materials and cuts in order to achieve temperature turnover within the measurement range (reference device) or high temperature drift (sensor),
- tiny dimensions (<1 mm×1 mm) for the sensor, **BUT** huge antenna \Rightarrow how to extend a horizontal dipole buried in ice ?
- single crystal materials \Rightarrow efficient modelling,
- commercially available solution for immediate use.
- in all experiments, the sink (PC + network) is the weak link ⇒ complement data transmission with non-volatile mass storage

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Work in progress aimed at getting rid of the dedicated interrogation electronics:

- use commercially available RF transcievers (UHF/SHF radiomodem with analog outputs) to probe SAW sensors
- find ways of using UHF SAW sensors (*f* ≤ 2.4 GHz) with widely available microwave RADARs (frequency conversion)
- merge SAW sensor measurement capability and WSN functionnalities (porting interrogator embedded sofware to TinyOS to take advantage of its MAC layer)

 \Rightarrow no/minor hardware modification to existing RADARs + software processing for using **acoustic sensors as cooperative targets**





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Perspectives

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HBAR manufacturing flowchart



- 1 4" wafer scale process
- 2 room temperature gold-eutectic bonding (high pressure)
- 3 if no access to buried electrode, coupled resonators
- 4 small resulting dimension ($<1 \text{ mm} \times 1 \text{ mm}$)
- **6 bulk** electrode \Rightarrow reduced aging and influence of environment (w.r.t IDTs)

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Generating acoustic waves

- Acoustic waves in solids: mechanical, thermal expansion, piezoelectric generation
- An RF voltage applied to an interdigitated transducer generates an acoustic wave¹¹
- Surface, bulk waves, shear/longitudinal/Rayleigh/ guided (Love mode)



• Delay line (single path) or resonator (reflectors define a cavity)

material	wave	(m/s)	TCF	comment
LiNbO ₃	shear	4700	-90 ppm/K	ferro. & pyroelectric, $T_C > 1200^{\circ}C$
LiTaO3	shear	4100	-36 ppm/K	$525 < T_C < 700^{\circ}$ C
KNbO ₃	Rayleigh	2800	$< 1 \; ppm/K$	huge coupling, $T_C \simeq 430^{\circ}$ C
	shear	3500	?	
LiB ₄ O ₇	Rayleigh	3500	-300 ppb/K ²	water soluble
langasite	Rayleigh	2900	-70 ppb/K ²	no Curie temperature, $> 1000^{o}$ C
Quartz	Rayleigh	3150	-40 ppb/K ²	most used
	shear	5100	-60 ppb/K ²	less coupled

11 R.M. White & F.W. Voltmer, Direct piezoelectric coupling to surface acoustic waves; Appl Phys. Letters 7 (12), 1965, 314-316) Q. (*)