

Outline

• Sub-surface pollution monitoring using Ground Penetrating RADAR (GPR) cooperative target

chemical sensing in water

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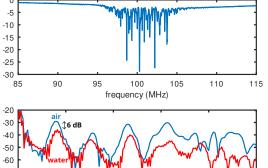
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Velocity v.s guiding layer thickness

- Transducer: surface acoustic wave **reflective delay line**
- Mirrors located for echoes in the 0.8 to 3.2 μ s range to avoid clutter
- Avoid capacitive short circuit when dipping sensor in water by selecting a high permittivity substrate: Lithium Tantalate ($\varepsilon_r \simeq 40$) leading to less than 6 dB loss when interdigitated electrodes covered with water ($\varepsilon_r \simeq 80$)
- compatible with commercial, off the shelf GPR with center frequency f_c of $\stackrel{\odot}{=}$ 100 or 200 MHz and bandwidth $0.14 \times f_c$ given by electromechanical coupling $\overline{2}_{c}$ -60 coefficient K^2 -80





time (us)

Lithium tantalate (LTO) shear wave gravimetric sensitivity

- 5000 • Shear wave propagation on a high permittivity substrate to avoid capacitive short circuit and remain com-(o) 4500 patible with measurements in liquid phase
- Metallized acoustic path to slow the wave and keep the $\frac{2}{2}$ pseudo-shear wave from radiating in the bulk
- Mirrors designed either for **mechanical** reflection or electrical re-emission
- Dielectric guiding layer for confining the surface acoustic wave in a Love mode
- Gravimetric sensitivity $S = \frac{df}{f} \cdot \frac{dm}{A}$ given by the slope of the velocity as a function of guiding layer thickness

Experimental results

- Wafer backside **roughened** to avoid interference between bulk acoustic wave and surface acoustic wave
- Sensor glued to Printed Circuit Board and wire bonded for electrical connection
- No fluidic for water confinement, especially not on the acoustic path erence
- Demonstration using non-specific protein adsorption from dehydrated milk
- nase di • Frequency domain characterization using vector network analyzer (e.g. NanoVNA and FreeVNA) and inverse Fourier transform for time-domain response

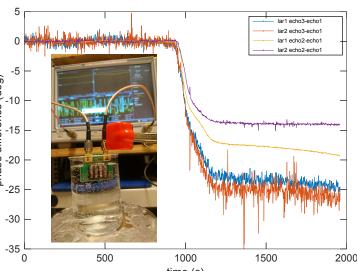
$$S_{11}(t) = 20 \times \log_{10}(iFFT(fftshift(S_{11}(f))))$$

• Dedicated functionalized polymer thin films for specific pollutant detection and Love mode guiding capability spread by spincoating for sub-micrometer thickness

Conclusions and perspectives

- Functional reflective delay line design on LTO
- Acceptable insertion loss when dipping sensor in water
- No microfluidic handling on the acoustic path
- Response compatible with commercial, off the shelf GPR
- Need for high long term stability of GPR timebase \Rightarrow selection of quartz-based clocked GPR (Sensors & Software) rather than RC-time constant circuit (Malå)

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Protein adsorption on LTO reflective delay line: experimental setup & result

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- D. Rabus, L. Arapan, P. Tanguy, J.-M Friedt, F. Chérioux, Sampling frequency fluctuations of the Sensors & Software SPIDAR GPR when probing passive surface aoustic wave delay lines for pollution sensing, IEEE Geoscience and Remote Sensing Letters 19 3503005 (2021)
- D. Rabus, J.-M. Friedt, L. Arapan, S. Lamare, M. Baqué, G. Audouin, F. Chérioux, Sub-surface H_2S detection by a Surface Acoustic Wave passive wireless sensor interrogated with a ground penetrating radar, ACS Sensors 5(4) 1075–1081 (2020)
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- J.-M Friedt, Passive cooperative targets for subsurface physical and chemical measurements, Proc. GPR2016 (2016)

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