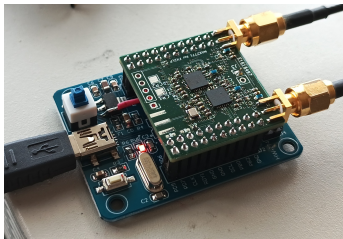


# Software defined radio receiver for multi-band GNSS reception

J.-M Friedt

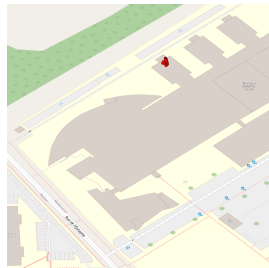
FEMTO-ST Time & Frequency, Besançon, France



to

```
> 2024 08 14 16 03 19.0000000 0 4
G13 26677805.858 7 140192817.566 7 3590.334 7 43.512
G14 28295834.916 6 148695547.549 6 4209.469 6 40.300
G30 25101222.820 8 131907837.064 8 1254.211 8 51.110
G20 24951215.267 7 131119518.199 7 896.314 7 47.843
> 2024 08 14 16 03 20.0000000 0 4
G13 26677119.759 7 140189224.429 7 3587.690 7 43.779
G14 28295031.757 6 148691334.164 6 4214.389 6 40.656
G30 25100981.910 8 131906580.351 8 1253.806 8 51.314
G20 24951039.364 7 131118617.388 7 896.117 7 47.906
> 2024 08 14 16 03 21.0000000 0 4
G13 26676437.663 7 140185631.373 7 3592.389 7 43.679
G14 28294218.270 6 148687120.773 6 4212.169 6 40.532
G30 25100742.929 8 131905324.028 8 1255.340 8 51.420
G20 24950866.874 8 131117717.063 8 898.874 8 48.169
> 2024 08 14 16 03 22.0000000 0 4
G13 26675749.902 7 140182037.428 7 3590.930 7 43.974
G14 28293419.650 6 148682906.377 6 4210.729 6 40.439
G30 25100500.429 8 131904067.112 8 1253.217 8 50.693
```

to



December 9, 2025

# Direction of arrival measurement<sup>1</sup>



- ▶ Condition for jamming/spoofing<sup>a</sup> cancellation: direction of arrival measurement...
- ▶ ... through phase analysis.
- ▶ Common clock driving all MAX2771...
- ▶ ... but internal PLL converting 24 MHz to targeted LO frequency

---

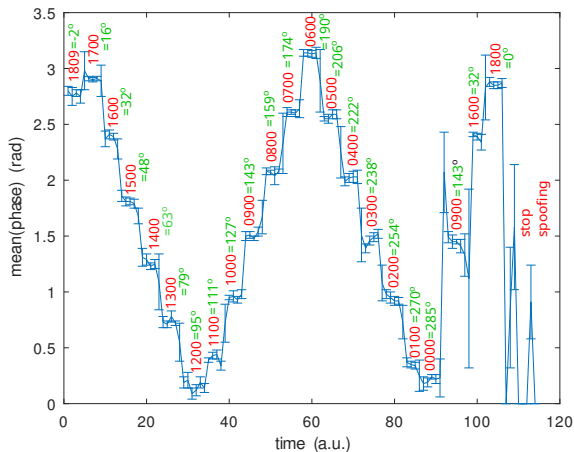
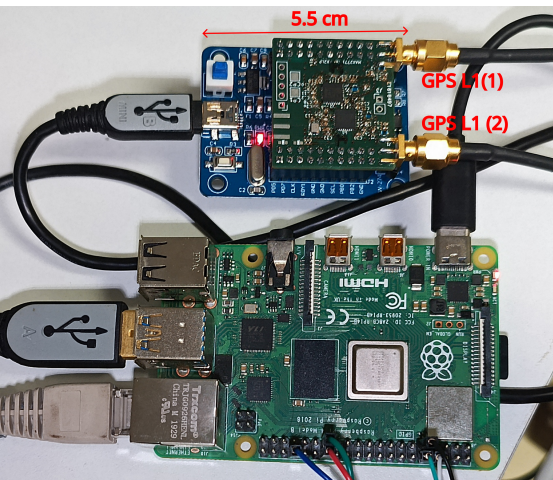
<sup>a</sup><https://developer.android.com/develop/sensors-and-location/sensors/gnss-spoof-jam> for single antenna jamming/spoofing indicators through AGC and SNR variations

---

<sup>1</sup><https://www.404media.co/ukraine-is-jamming-russias-superweapon-with-a-song/>

# Local oscillator drift

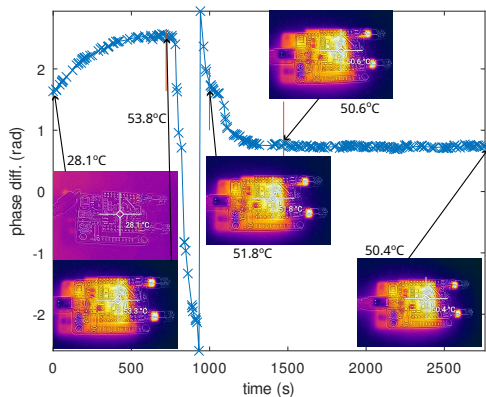
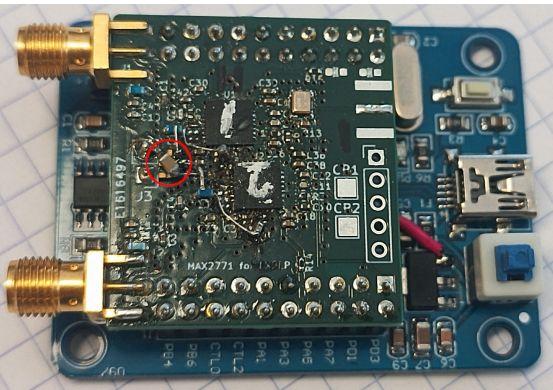
- ▶ DoA drift from PLL warming up<sup>2</sup>
- ▶ Oscillator drift and recalibration (5th overtone of 312.5 MHz oscillator<sup>3</sup>)



<sup>2</sup>[https://github.com/jmfriedt/max2771\\_fx2lp/tree/main/250610\\_calibrate\\_phase](https://github.com/jmfriedt/max2771_fx2lp/tree/main/250610_calibrate_phase)

# Local oscillator drift

- ▶ DoA drift from PLL warming up<sup>2</sup>
- ▶ Oscillator drift and recalibration (5th overtone of 312.5 MHz oscillator<sup>3</sup>)



<sup>2</sup>[https://github.com/jmfriedt/max2771\\_fx2lp/tree/main/250610\\_calibrate\\_phase](https://github.com/jmfriedt/max2771_fx2lp/tree/main/250610_calibrate_phase)

<sup>3</sup><https://www.mouser.fr/c/passive-components/frequency-control-timing-devices/oscillators/?frequency=312.5>

# RINEX file format

Standardized file format (Receiver INdependent EXchange): header indicates which signal are broadcast followed by time ending with number of satellites and data  $\Rightarrow$  `convbin -od -os file.ubx` from a Zed-F9P UBX receiver

```
3.04      OBSERVATION DATA      M: Mixed
CONVBIN demo5 b34g 20251203 070021 UTC
...
1208001.6727 260605.8262 6236717.5069
0.0000      0.0000      0.0000
G 4 C1C L1C C2X L2X
E 4 C1X L1X C7X L7X
2025 09 30 11 26 28.0000000 GPS
2025 09 30 11 31 31.0000000 GPS
G L1C
G L2X 0.00000
E L1X 0.00000
E L7X 0.00000
0
C1C 0.000 C1P 0.000 C2C 0.000 C2P 0.000
RINEX VERSION / TYPE
PGM / RUN BY / DATE
APPROX POSITION XYZ
ANTENNA: DELTA H/E/N
SYS / # / OBS TYPES
SYS / # / OBS TYPES
TIME OF FIRST OBS
TIME OF LAST OBS
SYS / PHASE SHIFT
SYS / PHASE SHIFT
SYS / PHASE SHIFT
SYS / PHASE SHIFT
GLONASS SLOT / FRQ #
GLONASS COD/PHS/BIS
END OF HEADER
```

```
> 2025 09 30 11 26 28.0000000 0 14
G05 21543121.518 113209866.8311
G07 22097456.951 116122919.1171
G09 22543808.581 118468513.3161
G16 22091705.362 116092693.9951
G21 21380460.846 112355079.4831
G27 24252145.735 127445885.0791
G29 24424801.384 128353197.0911
G30 23176153.781 121791509.6201
G26 24573984.906 129137161.0671
E08 25912171.769 136169381.3341
E05 24686094.961 129726303.8851
E03 24086786.604 126576917.0841
E16 26626116.477 139921185.7561
E24 25598232.306 134519618.2891
> 2025 09 30 11 26 29.0000000 0 14
G05 21542911.578 113208763.016
G07 22097219.518 116121671.135
G09 22544436.507 118471812.575
C16 22091020.488 116092876.158
```

```
3.04      OBSERVATION DATA      M: Mixed
CONVBIN demo5 b34g 20251203 070152 UTC
...
1208001.6727 260605.8262 6236717.5069
0.0000      0.0000      0.0000
G 8 C1C L1C D1C S1C C2X L2X D2X S2X
E 8 C1X L1X D1X S1X C7X L7X D7X S7X
2025 09 30 11 26 28.0000000 GPS
2025 09 30 11 31 31.0000000 GPS
G L1C
G L2X 0.00000
E L1X 0.00000
E L7X 0.00000
0
C1C 0.000 C1P 0.000 C2C 0.000 C2P 0.000
RINEX VERSION / TYPE
PGM / RUN BY / DATE
APPROX POSITION XYZ
ANTENNA: DELTA H/E/N
SYS / # / OBS TYPES
SYS / # / OBS TYPES
TIME OF FIRST OBS
TIME OF LAST OBS
SYS / PHASE SHIFT
SYS / PHASE SHIFT
SYS / PHASE SHIFT
SYS / PHASE SHIFT
GLONASS SLOT / FRQ #
GLONASS COD/PHS/BIS
END OF HEADER
```

```
> 2025 09 30 11 26 28.0000000 0 14
G05 21543121.518 113209866.8311 1105.702 47.000
G07 22097456.951 116122919.1171 1249.700 48.000
G09 22543808.581 118468513.3161 -3297.664 46.000
G16 22091705.362 116092693.9951 -1180.309 45.000
G21 21380460.846 112355079.4831 -1199.540 48.000
G27 24252145.735 127445885.0791 3252.296 42.000
G29 24424801.384 128353197.0911 -3235.472 40.000
G30 23176153.781 121791509.6201 2941.070 44.000
G26 24573984.906 129137161.0671 -3493.472 40.000
E08 25912171.769 136169381.3341 2539.786 43.000
E05 24686094.961 129726303.8851 -2827.162 43.000
E03 24086786.604 126576917.0841 -193.588 48.000
E16 26626116.477 139921185.7561 2588.755 48.000
E24 25598232.306 134519618.2891 1417.756 46.000
> 2025 09 30 11 26 29.0000000 0 14
G05 21542911.578 113208763.016 1102.126 47.000
G07 22097219.518 116121671.135 1246.281 48.000
G09 22544436.507 118471812.575 -3300.825 46.000
C16 22091020.488 116092876.158 -1182.954 45.000
```

# Raw GNSS from Android <sup>5</sup> <sup>6</sup>

- ▶ Google GNSSLogger stores raw information from visible satellites (pseudo-range, C/N0, Doppler...)
- ▶ <https://github.com/jorgeho1995/geagnss> for converting raw GNSSLogger files to RINEX<sup>4</sup> (see the `geagnss/tools/raw_android_to_rinex` subdirectory)



| Log |                                                                                   | Map  |           | Plots | Spoof/Jam |           | Status                                                                   | Measurements | Skyplot              | AGNSS                                                         | WLS Analysis |
|-----|-----------------------------------------------------------------------------------|------|-----------|-------|-----------|-----------|--------------------------------------------------------------------------|--------------|----------------------|---------------------------------------------------------------|--------------|
| ID  | GNSS                                                                              | Freq | Code Type | C/N0  | Rx SV     | Time (ns) | State                                                                    | PRR (m/s)    | ADR (m)              | ADR State                                                     |              |
| 13  |  | L1   | C         | 36.3  | 2.85e+14  | ± 5e+01   | [CODE_LOCK_BIT_SYNC, SUBFRAME_SYNC, TOW_DECODED, SYMBOL_SYNC, TOW_KNOWN] | -279 ± 0.150 | -8.13e+03 ± 0.000225 | [HALF_CYCLE_REPORTED, HALF_CYCLE_RESOLVED, VALID]             |              |
| 11  |  | L1   | C         | 31.6  | 2.85e+14  | ± 7e+01   | [CODE_LOCK_BIT_SYNC, SUBFRAME_SYNC, TOW_DECODED, SYMBOL_SYNC, TOW_KNOWN] | 797 ± 0.150  | 4.39e+04 ± 0.000625  | [CYCLE_SLIP, HALF_CYCLE_REPORTED, HALF_CYCLE_RESOLVED, VALID] |              |
| 21  |  | L1   | C         | 38.0  | 2.85e+14  | ± 5e+01   | [CODE_LOCK_BIT_SYNC, SUBFRAME_SYNC, TOW_DECODED, SYMBOL_SYNC, TOW_KNOWN] | 185 ± 0.150  | 1.49e+04 ± 0.000225  | [HALF_CYCLE_REPORTED, HALF_CYCLE_RESOLVED, VALID]             |              |
| 16  |  | L1   | C         | 15.8  | 2.85e+14  | ± 8e+02   | [CODE_LOCK_BIT_SYNC, SUBFRAME_SYNC, TOW_DECODED, SYMBOL_SYNC]            | 824 ± 0.150  | 0.00 ± 0.00          | [HALF_CYCLE_REPORTED]                                         |              |
| 12  |  | B1   | I         | 28.0  | 6.53e+05  | ± 2e+02   | [CODE_LOCK, MSEC_AMBIGUOUS]                                              | 309 ± 0.150  | 2.01e+04 ± 0.000900  | [HALF_CYCLE_REPORTED, VALID]                                  |              |
| 37  |  | B1   | I         | 31.3  | 2.85e+14  | ± 7e+01   | [CODE_LOCK, TOW_DECODED, BDS_D2_SUBFRAME_SYNC, TOW_KNOWN]                | 663 ± 0.150  | 3.52e+04 ± 0.000625  | [HALF_CYCLE_REPORTED, VALID]                                  |              |
| 5   |  | E1   | C         | 36.5  | 2.85e+14  | ± 5e+01   | [CODE_LOCK_BIT_SYNC, SUBFRAME_SYNC, TOW_DECODED, SYMBOL_SYNC, TOW_KNOWN] | 132 ± 0.150  | 1.67e+04 ± 0.000225  | [CYCLE_SLIP, HALF_CYCLE_REPORTED, HALF_CYCLE_RESOLVED, VALID] |              |

<sup>4</sup>J.H. Olcina & al, *Python toolbox for android GNSS raw data to RINEX conversion*, GPS Solutions 2895 (2024)

<sup>5</sup>GSA, *Using GNSS raw measurements on Android Devices* (2017) at

<https://galileognss.eu/wp-content/uploads/2018/05/Using-GNSS-Raw-Measurements-on-Android-devices.pdf>

<sup>6</sup><https://developer.android.com/develop/sensors-and-location/sensors/gnss-analyze-raw>

# Raw GNSS from Android <sup>7 8 9</sup>: dual frequency GNSS?

## Xiaomi MI10 (no L1C/L5C)

```

3.05      OBSERVATION DATA      M      RINEX VERSION / TYPE
Android RINEX 1.1  UPV      2025-11-23 18:25:12 PGM / RUN BY / DATE
GNSS00LOG      MARKER NAME
...
GNSSLogger
OBSERVER / AGENCY
M2007J17G      v2.0.0.1
REC # / TYPE / VERS
ANT # / TYPE
APPROX POSITION XYZ
ANTENNA: DELTA H/E/N
SYS / # / OBS TYPES
SYS / # / OBS TYPES
SYS / # / OBS TYPES
SYS / # / OBS TYPES
SYS / # / OBS TYPES
TIME OF FIRST OBS
END OF HEADER

2025 11 23 16 53 21.437459 GPS

> 2025 11 23 16 53 21.4374590 0 23
G12 23358459.413 -3114.539 29.600
G25 20541751.922 -1823.846 31.800 20539399.144 -1361.942 26.100
G28 20844050.629 587.900 26.300 20841700.224 439.019 29.800
G29 20400835.969 467.875 29.400
G31 21979772.713 2480.350 23.900
G26 23409762.286 2384.795 26.200
R14 19807427.951 1867.550 27.300
R22 22756753.780 -3731.700 17.800
...

```

## Ulefone (with L1C)

```

3.05      OBSERVATION DATA      M      RINEX VERSION / TYPE
Android RINEX 1.1  UPV      2025-11-23 18:25:44 PGM / RUN BY / DATE
GNSS00LOG      MARKER NAME
...
GNSSLogger
OBSERVER / AGENCY
Power Armor 19T GNSSv3.1.1.1
REC # / TYPE / VERS
ANT # / TYPE
APPROX POSITION XYZ
ANTENNA: DELTA H/E/N
SYS / # / OBS TYPES
SYS / # / OBS TYPES
SYS / # / OBS TYPES
SYS / # / OBS TYPES
SYS / # / OBS TYPES
TIME OF FIRST OBS
END OF HEADER

2025 11 23 16 53 22.000000 GPS

> 2025 11 23 16 53 22.0000000 0 19
G29 20368277.335 22732.374 -1174.150 32.910
G28 20811463.224 20673.754 -1055.922 27.857
G31 21946993.712 841.117 23.248
G25 20509425.920 63010.045 -3466.093 29.077
G11 23441642.589 -3161.024 20.836
G32 24083496.442 -4747.681 21.668
G26 23379250.382 1552.319 26.493
G18 25211231.428 2081.765 20.324
...

```

<sup>7</sup>V. Renaudin & al., *Positionnement GNSS précis sur smartphone : une réalité proche ?* (2020) à [https://cnig.gouv.fr/IMG/documents\\_wordpress/2020/11/4\\_VRenaudin\\_GNSS\\_smartphone.pdf](https://cnig.gouv.fr/IMG/documents_wordpress/2020/11/4_VRenaudin_GNSS_smartphone.pdf)

<sup>8</sup>T. Purfürst, *Evaluation of Static Autonomous GNSS Positioning Accuracy Using Single-, Dual-, and Tri-Frequency Smartphones in Forest Canopy Environments*, MDPI Sensors **22**(3) 1289 (2022)

<sup>9</sup>U. Robustelli & al., *Assessment of Dual Frequency GNSS Observations from a Xiaomi Mi 8 Android Smartphone and Positioning Performance Analysis*, MDPI Electronics **8**(1) 91 (2019)

# Raw GNSS from LuGRE <sup>13</sup>

- ▶ <https://zenodo.org/records/16411687> and <https://github.com/NavsasPolito/LuNART>
- ▶ Galileo time to GPS time offset<sup>10</sup>, GGTO, is broadcast with an accuracy better than 5 ns
- ▶  $\Rightarrow$  Galileo and GPS pseudoranges can be mixed in finding the PVT solution
- ▶ videos of the LuGRE data release workshop <sup>11</sup> in `/home/jmfriedt/LuGRE` (4 half-days <sup>12</sup>)

---

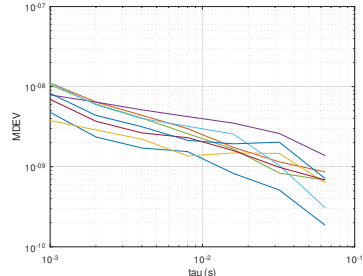
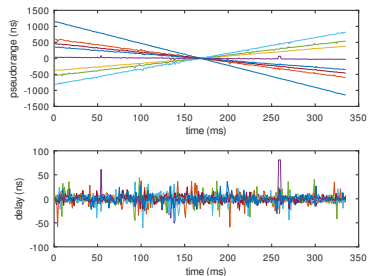
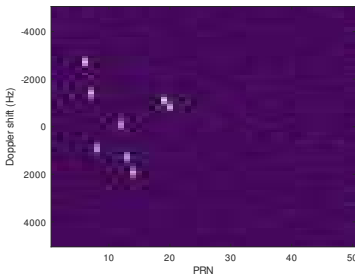
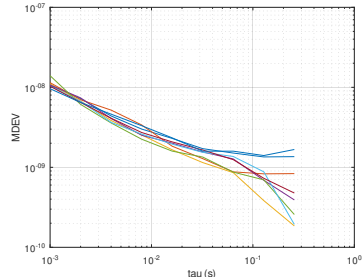
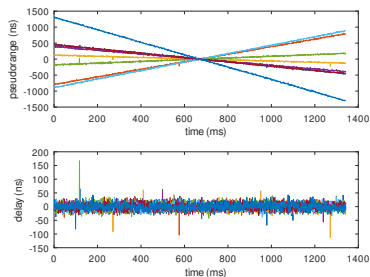
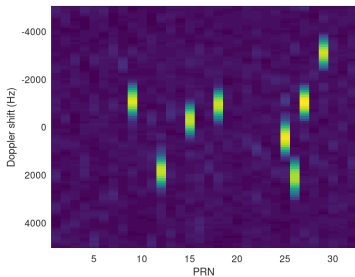
<sup>10</sup>[https://www.esa.int/Applications/Satellite\\_navigation/Galileo\\_and\\_GPS\\_synchronise\\_watches\\_new\\_time\\_offset\\_helps\\_working\\_together](https://www.esa.int/Applications/Satellite_navigation/Galileo_and_GPS_synchronise_watches_new_time_offset_helps_working_together)

<sup>11</sup><https://www.asi.it/en/event/lunar-navigation-and-exploration/>

<sup>12</sup><https://www.polito.it/en/polito/communication-and-press-office/poliflash/lugre-mission-nasa-and-asi-release-landmark-lunar-experiment>

<sup>13</sup>LuGRE sets another record: first GNSS signals detected in lunar orbit (21 February 2025) at <https://www.asi.it/en/2025/02/lugre-sets-another-record-first-gnss-signals-detected-in-lunar-orbit/>

# Raw GNSS time transfer: manual xcorr v.s gnss-sdr pseudo ranges

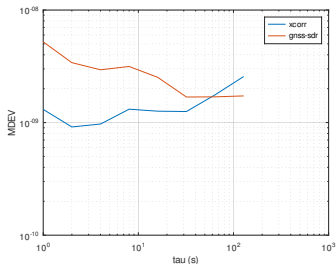
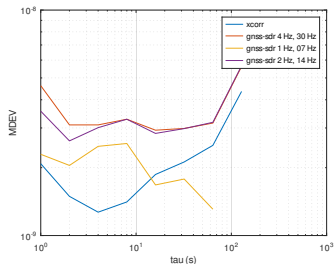
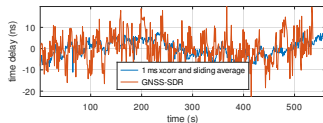
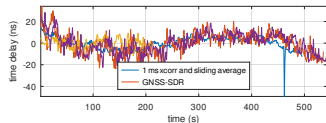
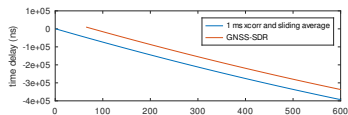
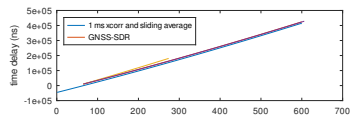


# Manual xcorr calculation v.s. gnss-sdr pseudoranges

900 s long record, 16 bit samples collected by 2-X310s clocked by HM and 1-PPS, sampling @ 5 MS/s  
PRN25:

PRN25:

- ▶ At the beginning, acquisition for coarse Doppler shift estimate for visible SVs
- ▶ GPS L1: cross-correlate 1-ms long batches, oversample ( $\times 3$  by zero-padding) and parabolic fit of cross-correlation peak magnitude
- ▶ sliding average over 1000 estimates (1-s long equivalent): top
- ▶ remove parabolic fit of SV trajectory (top to middle)
- ▶ compare with gnss-sdr pseudo-range for the same SV ( $/3 \cdot 10^8 \times 10^9$  ns) (bottom for modified Allan deviation result):



```
Tracking_1C.implementation=GPS_L1_CA_DLL_PLL_1;
Tracking_1C.pll_bw_hz=30.0;
Tracking_1C.dll_bw_hz=4.0;
Tracking_1C.order=3;
Tracking_1C.early_late_space_chips=0.5;
```