

# Passive RADAR interrogation of passive cooperative targets: long range illumination of SAW delay lines using high power sources



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**Slides** at <http://jmfriedt.free.fr/sawsymposium2021.pdf>

sequel to M. Paquit & al., *Long range passive RADAR interrogation of subsurface acoustic passive wireless sensors using terrestrial television signals*, IEEE Sensors **20** (13) 7156–7160 (2020)



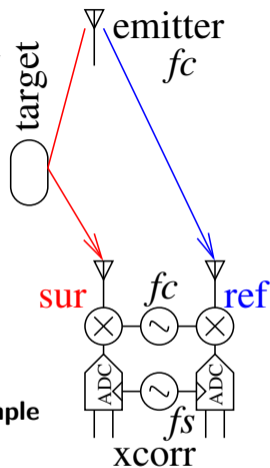
<https://www.ettus.com/>  
<https://www.kubii.fr/>

# Passive bistatic RADAR (PBR)

- ▶ Passive RADAR: using existing electromagnetic sources for RAdiofrequency Detection And Ranging (time delay and Doppler shift for target velocity)
- ▶ Popular with universities and amateurs: no need to be allowed to emit a strong signal ( $P_R \propto P_E/d^4$ )
- ▶ Range resolution solely determined by bandwidth  $\Delta f$   
 $\Delta R = c/(2\Delta f) \Rightarrow \Delta f \nearrow \Rightarrow \Delta R \searrow$
- ▶ Beamwidth  $\simeq$  azimuth resolution determined by antenna size wrt  $\lambda$
- ▶ Synthetic Aperture RADAR: move transmitting and/or receiving antenna to simulate a large aperture and hence improved azimuth resolution

Demonstrated using Ettus Research E312 or <sup>1</sup> B210 <sup>2</sup> <sup>3</sup> SDR platforms using frequency stacking.

**Need for two coherent (same LO, same sampling rate) channels to sample reference and surveillance signals**



<sup>1</sup>S.T. Peters & al., *In Situ Demonstration of a Passive Radio Sounding Approach Using the Sun for Echo Detection*, IEEE Trans. Geosci. and Remote Sensing **56** (12) 7338 (Dec. 2018)

<sup>2</sup>S. Prager & al., *Ultrawideband Synthesis for High-Range-Resolution Software-Defined Radar*, IEEE Trans. Instrum. Meas. **69** 3789–3803 (2020)

<sup>3</sup>O. Toker & al., *A Synthetic Wide-Bandwidth Radar System Using Software Defined Radios*, 7th International Electronic Conference on Sensors and Applications (15–30 November 2020)

# Passive wireless cooperative target

- ▶ Design considerations
  - ▶ separate relevant signal from clutter: delay echo by at least  $1 \mu\text{s}$
  - ▶ compact: avoid 100 m coaxial cable to delay by  $1 \mu\text{s}$  two-way trip
  - ▶ sensing capability: delay dependence with physical environment
- ⇒ acoustic delay line since most non-cooperative sources will be wideband ( $\neq$  resonator)
- ▶ Deployment scenario: passive wireless sensor buried in concrete/soil and periodically probed
- ▶ Challenge: radiofrequency emission **regulations**

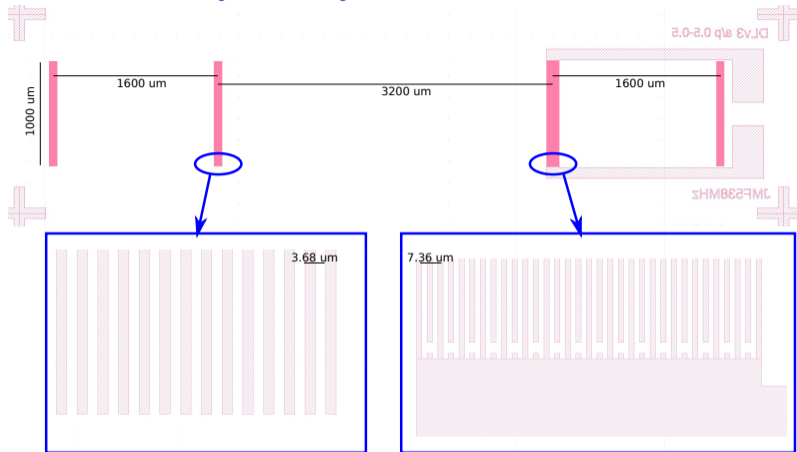
Use existing high power broadband sources to illuminate SAW delay line and short range reception of the signal



## SAW delay line as cooperative target for non-cooperative source PBR measurement <sup>4</sup>

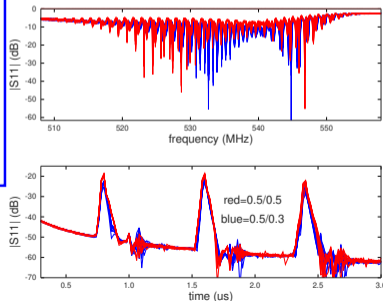
<sup>4</sup>M. Paquit & al., *Long range passive RADAR interrogation of subsurface acoustic passive wireless sensors using terrestrial television signals*, IEEE Sensors **20** (13) 7156–7160 (2020)

# Reflective delay line layout



128° LNO:  $K^2 \approx 5.7\%$ : sensor bandwidth  $\approx 31$  MHz @ 538 MHz,  $1/K^2$  finger pairs<sup>5</sup> in inter-digited transducer (IDT)

- ▶ YXI/128° LNO
- ▶ 50% or 70% metallization ratio
- ▶ aperture=1000  $\mu\text{m}$
- ▶ floating potential ...
- ▶ ... reflective mirrors
- ▶ delays T, 2T, 3T (T=870 ns)
- ▶ chip size: 7200  $\mu\text{m} \times 1800 \mu\text{m}$
- ▶ 20 dB time-domain insertion losses



<sup>5</sup>D. Morgan, *Surface Acoustic Wave Filters – With Applications to Electronic Communications and Signal Processing, 2nd Ed.*, Academic Press (2007), pp.158–160, & teaching by V. Plesky

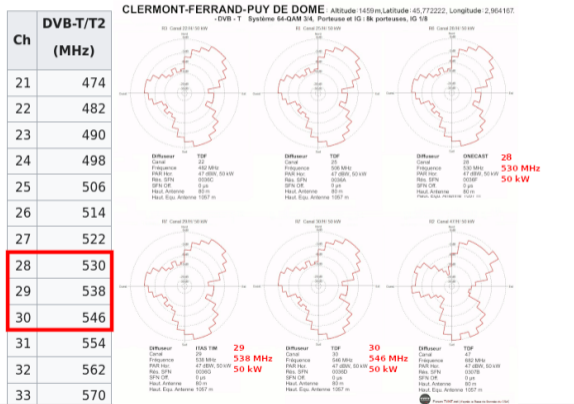
# Digital Video Broadcast-Terrestrial non-cooperative source

Static emitter (e.g. DVB-T or GSM tower), static or moving receiver(s)

- ▶ 128° LNO:  $K^2 \simeq 5.7\%$ : sensor bandwidth  $\simeq 31$  MHz
- ▶ DVB-T 8 MHz wide channels but ...
- ▶ ... Clermont Ferrand (45.7726 N, 2.9644 E) transmits DVB-T on three adjacent channels (European 28, 29 and 30) centered on 530, 536 and 546 MHz.
- ▶ 11.8 km range to the 1465 m high emitter
- ▶ One 6-element directional Yagi-Uda antenna towards reference signal and a dipole in close contact to the surface holding the sensor connected to a dipole antenna (cf Ground Penetrating RADAR layout)



[https://en.wikipedia.org/wiki/Television\\_channel\\_frequencies](https://en.wikipedia.org/wiki/Television_channel_frequencies)  
**DVB-T/DVB-T2/DTMB/ISDB-T Digital television frequencies (Western Eastern Europe most countries Asia, Africa and Oceania [ edit ]**

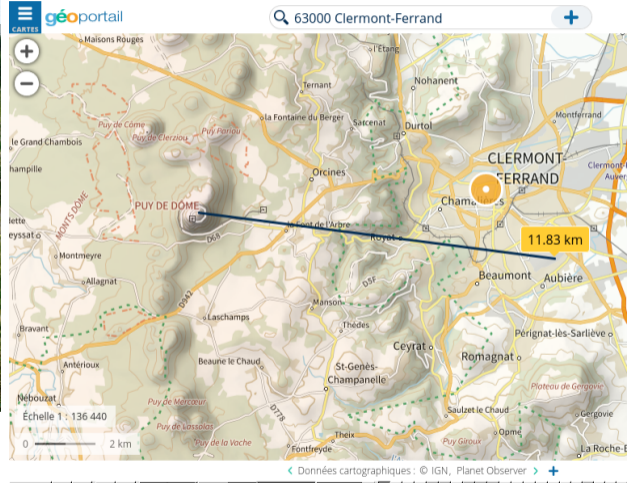


Puy du Dôme DVB-T emitter characteristics

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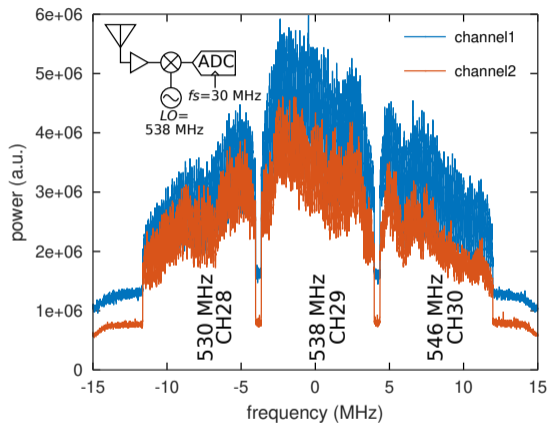


Geographical settings

# Hardware for radiofrequency signal reception

- ▶ SDR: bandwidth challenge
- ▶ USB3 on RPi4 for maximum transfer bandwidth + avoid the Ethernet/USB sharing bottleneck of RPi3
- ▶ single channel B210 measurement: 56 Msamples/s ...
- ▶ ... streamed to 8 GB RAM Raspberry Pi 4 (RPi 4) and stored to RAMdisk.
- ▶ Custom software <sup>6</sup> for transferring **8-bit data** (Over The Wire (otw) format) and storing 8-bit IQ samples to file
- ▶ RPi4 6 GB/56 MS/s IQ bytes=57 second records
- ▶ RPi4 6 GB/2×30 MS/s IQ bytes=53 seconds
- ▶ AD9361 radiofrequency frontend local oscillator  $\in [70 : 6000]$  MHz
- ▶ Baseband spectrum displays the three channels  $\rightarrow$
- ▶ Switch the RPi4 to “performance” (1.5 GHz clock rate) mode:

```
echo performance > /sys/devices/system/cpu/cpu0/cpufreq/scaling_governor
```

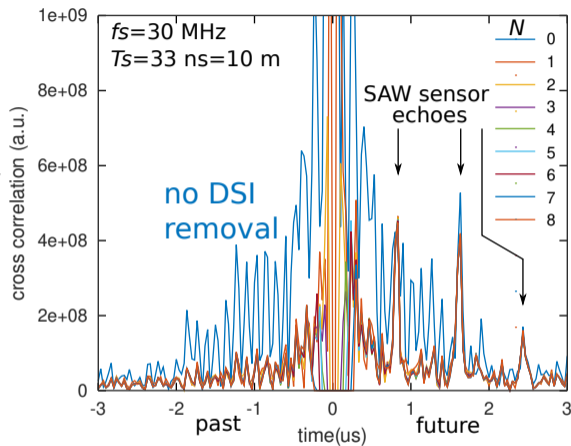


<sup>6</sup>[https://github.com/jmfriedt/sentinel1\\_pbr/](https://github.com/jmfriedt/sentinel1_pbr/)

# Signal extraction: direct signal interference (DSI) removal

- ▶ The surveillance channel receives the direct signal from the emitter as well
- ▶ The DVB-T is not exactly noise (autocorrelation=Dirac) but includes some repetitive structure in time and frequency (ambiguity function  $\int s(t)s^*(t-\tau)\exp(j2\pi ft)\cdot dt$  = autocorrelation when Doppler shift is null)
- ▶ Identify direct signal from reference antenna and subtract from surveillance shifted  $n$  times,  $n \in [0 : N]$  with  $N$  large enough to remove multipath but small enough to keep target echoes
- ▶ weights identified as least square error solution<sup>7</sup>: assemble matrix of time-delayed copies of reference measurement, and pseudo-inverse to identify weight of each vector in surveillance:  $\rightarrow$

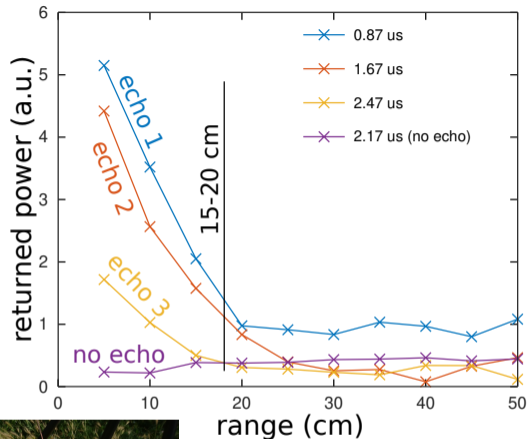
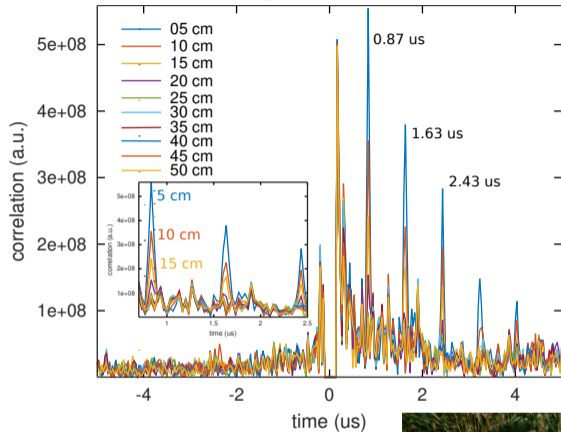
<sup>7</sup> W. Feng, J.-M. Friedt, G. Cherniak, Z. Hu, M. Sato, *Direct path interference suppression for short range passive bistatic SAR imaging based on atomic norm minimization and Vandermonde decomposition*, IET Radar, Sonar and Navigation (2019)



```
Index1=0:N;Index2=N; % analyze delay N*dt, could be positive only
num_range_shift=(Index2-Index1+1); % if ref channel is known
X1=zeros(num_range_shift, num_range_shift);
for kk=Index1:Index2 % by W. Feng & al
    te=kk+abs(Index1)+1;
    if kk<=0 X1(:,te)=[signal_ref(0-kk+1:end); zeros(0-kk,1)];
        else X1(:,te)=[zeros(kk-1,1); signal_ref(1:end-kk+1)]; end
end
signal_meas=signal_meas-X1*(pinv(X1)*signal_meas); % least square
```



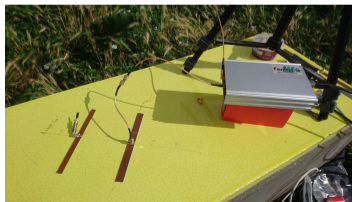
# Measurement range assessment



$$sur = sur - X \cdot \underbrace{(X^t \cdot X)^{-1} X}_{\text{pinv}(X)} \cdot sur$$

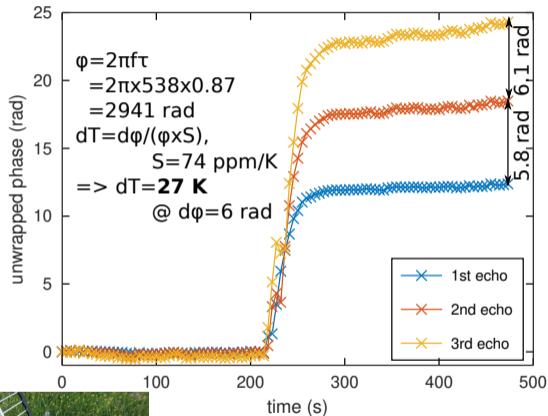
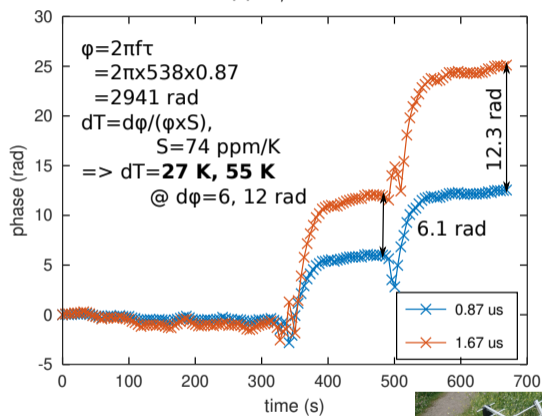
weights

$$xcorr = iFFT[FFT(ref) \cdot FFT^*(sur)]$$



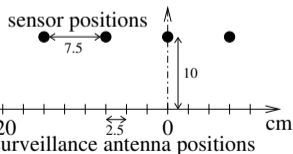
# Temperature measurement

- ▶ Range from surveillance dipole to sensor dipole: 10 cm – lighter heating the sensor
- ▶  $128^\circ$  LNO:  $\approx 74$  ppm/K

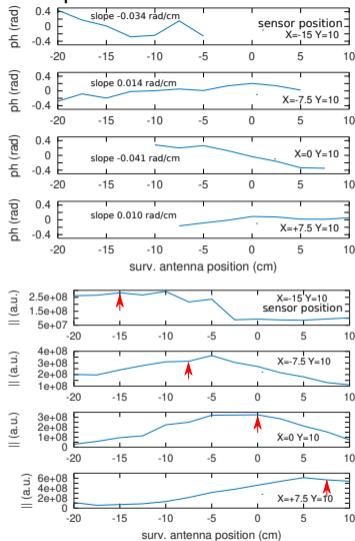


# Spatial separation of sensors

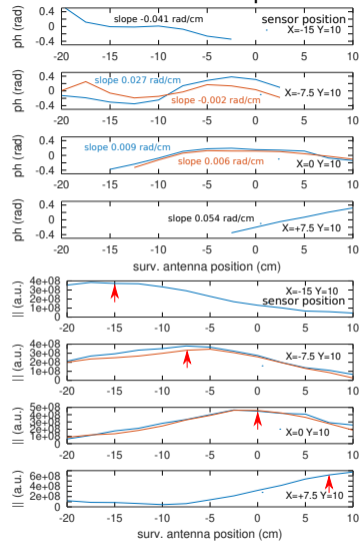
- ▶ Matrix ( $M \times N$ ) with  $M$  time-domain acquisitions for  $N$  surveillance antenna positions separated by  $\Delta d < \lambda/2$
- ▶ Range compression: correlation along time axis ( $M$  items)
- ▶ Phase along azimuth:  $\varphi = 2\pi \frac{\Delta d}{\lambda} \sin \vartheta_0$
- ▶ Synthetic aperture RADAR azimuth compression<sup>8</sup>: iFFT along surveillance antenna positions ( $N$  items)
- ▶ Here near field measurement:  $\max(|\text{returned power}|)$  hints at sensor position along measurement line



## Experiment1



## Phase



## Magnitude

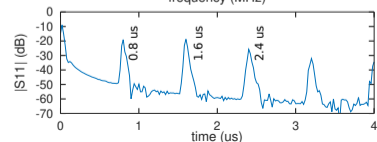
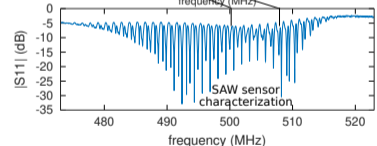
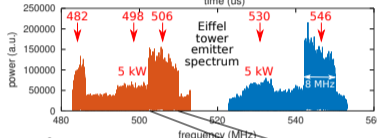
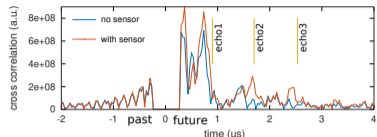
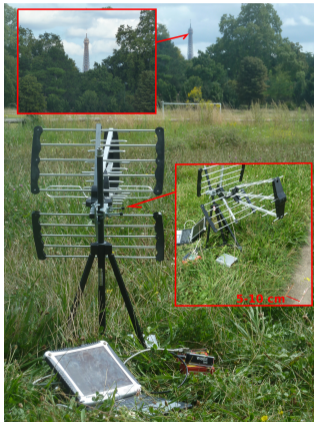
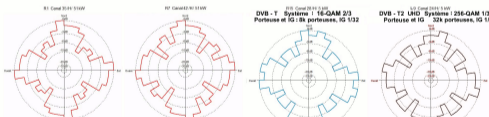
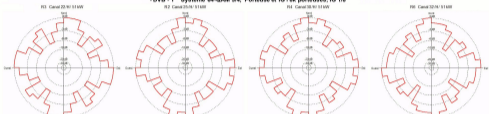
<sup>8</sup>W. Feng, J.-M. Friedt, G. Goavec-Merou, M. Sato, *Passive radar delay and angle of arrival measurements of multiple acoustic delay lines used as passive sensors*, IEEE Sensors **19** (2) 594–602 (2019)

# Same in Paris ... Eiffel tower, measurement 4.25 km away

- ▶ 50 kW at 482 and 506 MHz (32 MHz wide) and tentative 5 kW @ 498 & 530 MHz

PARIS TOUR EIFFEL : Altitude 33 m, Latitude 48.858333, Longitude 2.294444

DVB - T Systeme 64-QAM 3/4, Porteuse et IG : 8k portuses, IG 1/8



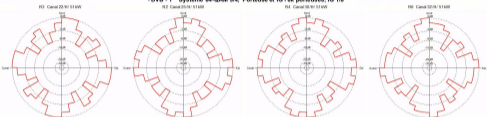
Only a single channel in each 30-MHz wide band.

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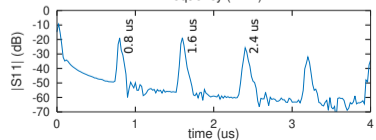
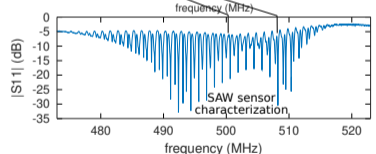
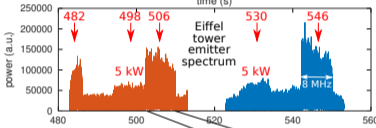
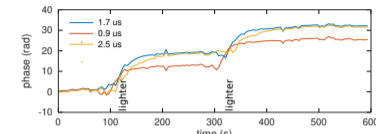


**Difusor** TDF  
Canal 32  
Fréquence 482 MHz  
PWR Max 47.1 dBW, 50 kW  
Mod. SFN 0001A  
SFN CA 0 µs  
Haut. Antenne 313 m  
Haut. Equ. Antenne 310 m

**Difusor** TDF  
Canal 25  
Fréquence 498 MHz  
PWR Max 47.1 dBW, 50 kW  
Mod. SFN 0001B  
SFN CA 0 µs  
Haut. Antenne 313 m  
Haut. Equ. Antenne 310 m

**Difusor** TDF  
Canal 38  
Fréquence 506 MHz  
PWR Max 47.1 dBW, 50 kW  
Mod. SFN 0001C  
SFN CA 0 µs  
Haut. Antenne 313 m  
Haut. Equ. Antenne 310 m

**Difusor** TDF  
Canal 34  
Fréquence 530 MHz  
PWR Max 47.1 dBW, 50 kW  
Mod. SFN 0001D  
SFN CA 0 µs  
Haut. Antenne 313 m  
Haut. Equ. Antenne 310 m



Consistent temperature measurement @ 4.5 cm.

# How does it compare with energy harvesting?

Series of investigations at Univ. of Tôkyô on rectenna for electromagnetic smog energy harvesting

- ▶ H. Nishimoto, Y. Kawahara, T. Asami, *Prototype Implementation of Ambient RF Energy Harvesting Wireless Sensor Networks*, IEEE Sensors conference (2010)
- ▶ R. Vyas, H. Nishimoto, M. Tentzeris, Y. Kawahara, T. Asami, *A battery-less, energy harvesting device for long range scavenging of wireless power from terrestrial TV broadcasts*, Proc. IEEE MTT-S International Microwave Symposium (2012)
- ▶ R.J. Vyas, B.B. Cook, Y. Kawahara, M. Tentzeris, *E-WEHP: A Batteryless Embedded Sensor-Platform Wirelessly Powered From Ambient Digital-TV Signals*, IEEE Trans. Microwave Theory and Techniques (2013)



6.3 km from Tôkyô Tower to Univ. of Tôkyô Hongo campus: -9 dBm resulting from -37 dBm integrated over 9 channels (54 MHz bandwidth) to power a MSP430 & PIC24F low-power microcontrollers + radiofrequency digital communication interface **but 60 s charge time**

**This work:** 77 dBm emitted at a range of 11.8 km  $\Rightarrow$  Free Space Propagation Loss leads to -31.5 dBm received power at SAW sensor with 20 dB loss  $\Rightarrow$  -51.5 dBm backscattered power and Free Space Propagation Loss to surveillance: -58.5 dBm received power ideally @ 10 cm =  $266 \mu V_{RMS}$  **but 1 MS correlation collected in 30 ms**

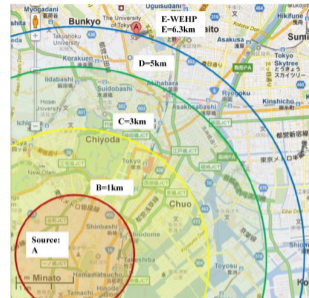


Fig. 3. Location of Tokyo TV broadcast source at A ( $35^{\circ}39'31''$  N  $139^{\circ}44'44''$  E) with respect to E-WEHP at E ( $35.712704$  N,  $139.763277$  E) 6.3 km away.

TABLE II  
THEORETICAL AND MEASURED SINGLE-CARRIER AND CHANNEL POWER LEVELS USING E-WEHP ANTENNA (GAIN: 5–7.3 dB)

TV Channel Freq. (MHz)		A P <sub>TX</sub> Power kW	B 1km $\mu$ W	C 3km $\mu$ W	D 5km $\mu$ W	E 6.3km $\mu$ W	
						theo ry	meas
JOMX 512-518	1-tone	5	0.32	0.26	0.21	0.19	0.008
	Chan nel		37.3	30.3	24.5	22.1	0.93
JO- RX/CX/TX/ EX/AX/AB /AK 518-560	1-tone	48	3.6- 4.1	2.9- 3.4	2.3- 2.7	2.2- 2.5	0.1- 0.25
	Chan nel		419- 478	338- 396	268- 315	256- 291	11.7- 29
JOUR 560-566	1-tone	19	1.37	1.08	0.86	0.78	0.032
	Chan nel		160	126	100	91	3.73

# Conclusion

- ▶ Demonstration of long range (>10 km) powering of SAW delay line for short range (<20 cm) passive wireless transducer probing in the context of shallow buried sensors
- ▶ Embedded, COTS hardware for passive bistatic RADAR probing of cooperative targets
- ▶ Demonstration with VHF SAW reflective delay lines and DVB-T transmitters.
- ▶ Need for subtracting Direct Signal Interference to recover SAW sensor backscattered signal.

**Dresden - MUX-SACH**  
DVB-T transmitter in Germany

< Return to previous page | DVB-T transmitters list by country | DVB-T Radar | DVB-T Bitrate Calculator

Check also other multiplexes from Dresden transmitter:  
MUX-ARDN (ch. 39), MUX-ZDF (ch. 36)

Transmitter address: **Transmitter: Dresden**  
Country: Germany

Latitude: 51°N 03' 23"  
Longitude: 13°E 50' 19"

Multiplex name: Multiplex Sach

Channel number	Frequency	Channel width	Polarisation	ERP power
29	538 MHz	8 MHz	Vertical	100 kW



S. Müller, wikimedia.org

**München - Olympiaturm - MUX-ZDF**  
DVB-T transmitter in Germany

< Return to previous page | DVB-T transmitters list by country | DVB-T Radar | DVB-T Bitrate Calculator

Check also other multiplexes from München - Olympiaturm transmitter:  
MUX-ARDS (ch. 54), MUX-BRS (ch. 56), MUX-MUN (ch. 66), MUX-PRO7 (ch. 48), MUX-RTL (ch. 34)

Transmitter address: **Transmitter: München - Olympiaturm**  
Country: Germany

Latitude: 48°N 10' 28"  
Longitude: 11°E 33' 13"

Multiplex name: Multiplex ZDF

Channel number	Frequency	Channel width	Polarisation	ERP power
35	586 MHz	8 MHz	Vertical	100 kW



Taxiarchos228, wikimedia.org

Applicable throughout Europe at least (example of German emitters: 100 kW EIRP) & China <sup>9</sup>

<sup>9</sup><http://www.com-tech.it/download/ChannelStructure.pdf>